SCHOOL OF AEROSPACE, MECHANICAL & MECHATRONIC ENGINEERING

RESEARCH REPORT 2011





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Designed and produced in-house by the School of Aerospace, Mechanical & Mechatronic Engineering, University of Sydney



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Professor Steve Armfield Head of School

We are pleased to publish this report which reflects the research strengths and achievements in the School of Aerospace, Mechanical and Mechatronic Engineering (AMME) for 2011. The school has a number of world class research groups and has continued to maintain its position as the dominant research school in the faculty, and one of the leading engineering research schools in the country. During the year \$5.5 million of new research funding was obtained, 311 research articles and books were published, 125 research students were under supervision and 16 research students completed. With 29 permanent academic staff members our performance per capita places us on a par with the top engineering schools in the world. I would like to thank all the staff whose hard work and dedication has produced this outstanding research profile, and in particular to congratulate Professor Yiu-Wing Mai on being elected an International Fellow of the Royal Academy of Engineering and Professor Roger Tanner for completing 40 years of service to the University.

Organisational Overview

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Academic Staff

Head of School

Prof Steve Armfield

Professors

Armfield, Steven
Behnia, Masud
Mai, Yiu-Wing
Masri, Assaad (ARC
Australian Professorial
Fellow)
Nebot, Eduardo
Tanner, Roger
Tong, Liyong
Ye, Lin

Emeritus Professors

Bilger, Robert Bird, Graeme Steven, Grant

Honorary Professors

Brandwood, Arthur Carter, Paul Henderson, Le Roy Kent, John

Adjunct Professor

Chamitoff, Gregory

Associate Professors

Dunstan, Colin Li, Qing Liao, Xiaozhou (ARC Fellow QEII) Ruys, Andrew Rye, David Sukkarieh, Salah Williams, Stefan Zreiqat, Hala (NHMRC Senior Research Fellow)

Honorary Associate Professors

Diwan, Ashish Wong, Shing-Chung

Adjunct Associate Professors

Lowe, Allen Parsi, Kurosh Roger, Greg Zheng, Rong

Senior Lecturers

Auld, Douglass (Associate Dean, Education) Brooker, Graham Gibbens, Peter Karkenahalli, Srinivas (Deputy Head of School) Jabbarzadeh, Ahmad Kirkpatrick, Michael McHugh, Paul Wong, Kee Choon

Honorary Senior Lecturers

Bilston, Lynne Tran, Giang

Lecturers

Li, Chang Wu, Xiaofeng Verstraete, Dries Vio, Gareth

Honorary Lecturers

Boughton, Phillip Stone, Hugh

Adjunct Lecturer

Bates, Peter

Associate Lecturers

Briozzo, Paul Fiford, Rod

Honorary Associates

Clarke, Elizabeth Fan, Xijun Houghton, Ron Lu, Chunsheng Mitra, Ashish Qin, Qing Hua Shah, Shruti Swain, Michael Zhang, Xin-Ping

Research Staff

ARC Future Fellow

Liu, Hong Yuan

ARC Australian Research Fellow

Li, Wei

ARC Postdoctoral Research Fellows

Pizarro, Oscar Wang, Yanbo Williamson, Nicholas

ARC Postdoctoral Fellow- Industry

Nagarathinam, Srinarayana

ARC Research Associate

Tekyeh Marouf, Bahereh

Australian Postdoctoral Fellow

Lu, Ye

University of Sydney Postdoctoral Fellow

Yang, Chuncheng

CRC-ACS Postdoctoral Fellow

Islam, Saiful Mohammad

Research Fellows

Allen, Thomas Elinas, Pantelis Fitch, Robert Göktoğan, Ali Hatherly, Peter Hill, Andrew Johnson, David Johnson-Roberson, Matthew Melkumyan, Arman Monteiro, Sildomar Takahashi Murphy, Richard Nieto, Juan Nourani-Vatani, Navid Orchansky, David Scheding, Steven Underwood, James Vasudevan, Shrihari Velonaki, Mari Worrall, Stewart Zhou, Hang (Cathy) Peynot, Thierry

Post Doctoral Fellows

Aberra, Tilek Bailey, Tim Baji, Avinash Bryson, Mitchell Chen, Yuhang Dai, Shao Cong Juddoo, Mrinal Kittipoomwong, Prakorn David Lee Wo, Duane Luo, Quantian Qi, Fuzhong Starner, Sten Tang, Youhong Zhou, Shiwei

Postdoctoral Research Associates

Chen, Bin Du, Xusheng Kourmatzis, Agisilaos Lu, ZuFu Nakul, Vinayaka Prasad Wang, Guocheng

Postdoctoral Researcher

Wang, Dong

Organisational Overview

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Research Staff

Research Associates

Bertevas, Erwan Deng, Shiqiang Douillard, Bertrand Lawrance, Nicholas Ramos, Fabio Reid, Alistair Rungsiyakull, Chaiy Uthayakumaran, Surjani

Senior Research Engineer (CRC-AS) Beehag, Andrew

Research Assistant

James, Barbara

Administrative Staff

Administration Personnel

Liang, Wendy (Undergraduate Studies) Martin, Vinita (Head of School's Office) Olip, Ruth (Admin Manager, ACFR) Santos, Tessie Sawtell, Olga (CEO, Operations, ACFR) Sexton, Bronwyn (Postgraduate Studies & Marketing)

Finance Managers

Connell, Robin Wang, Christy

Finance Officer

Joshi, Padmini

Administrative Assistants

Gonzales, Susan Hunter-Smith, Lisa (ACFR)

Workshop Staff

Senior Technical Officers

Elder, Greg (Deputy Manager, AMME Workshop) Stenger, Duncan (Manager, AMME Workshop)

Technical Officers

Blekhman, Alexander Brown, Stuart

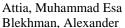
Calleija, Mark Chan, Victor Chen, Quanjun (Jerry) Crundwell, Bruce Durrant, Andrew Geier, Matthew Goyal, Abhinav Hale, Tim Hennessy, Ross Karkada, Stanley Lal, Ritesh Lees, Christian Leung, Raymond Lowe, Alex

Maclean, Andrew Martinez, Javier Massey, Alexander McCouat, Nicholas Merry, Laura Miller, Tim Nguyen, Dai Bang O'Shannessy, Robert Ralph, Daniel Randle, Jeremy Riviere, Greg Shearing, Trevor Sinclair, Malcolm Todhunter, John

Vitjuk, Ivan Vlaskine, Vsevolod Wishart, Stuart Wohlleber, Cedric Wright, James Zigman, John

Technical Assistants

Mear, Paul Potts, John









Organisational Overview

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Visiting Professors/ Scholars

Bussiba, Arry Fan, Jin-tu Gong, Xiao-Jing Hosoi, Atsushi Lee, Jim Nettleton, Eric Pyrz, Ryszard Raman, Venkatramanan Wei, Kexiang Wu, Jingshen

Yang, Ying-Kui Yu, Zhong-Zhen Zhang, Donghai Zhou, Limin

Occupational Trainees

Cazzato, Luigi Fu, Kunkun Gang Yang, Miao Hagel, Philipp Hattori, Gabriel Da Silva Huang, Yuan-Li Jiang, An Matela, Michael Qin, Guo Shou, Dahua Sun, Jingli Torkittikul, Pincha Wang, Chao Witt, Nikolai Won, Dae-Yeon Zhu, Suqin

Research Highlights

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Research and Teaching Grants Awarded in 2011

Australian Research Council (ARC) Discovery Grants

MAI and Guo \$345,000

Toughening thermosets by highly ordered nanostructures

LIAO and Wang \$300,000

Interactions between linear and interfacial crystalline defects and their impact on mechanical properties in nanostructured metals and alloys

Australian Research Council (ARC) Future Fellowship

LIAO \$817,856

The effect of structure and size on the mechanical behaviour of III-V semiconductor nanowires

WILLIAMS \$759,836

Delivering information suitable for studying spatial and temporal variability in benthic habitats using autonomous underwater vehicles

Australian Research Council (ARC) Linkage Grant

NEBOT, Nieto and Brooker \$480,800

Development of fundamental perception technology and algorithms for mining safety

Australian Research Council (ARC) Linkage Infrastructure, Equipment and Facilities Grant (LIEF)

LIAO \$200,000

Joint processing facility for the production of far-from-equilibrium alloy structures

Australian Research Council (ARC) Discovery Early Career Researcher Awards (DECRA)

TANG \$375,000

Water-swellable rubber with nanoparticleenabled super capacity as smart water-leakage

ZHOU \$375,000

Topology optimisation for advanced engineered nanostructures

National Health and Medical Research Council Grant (NHMRC) Project Grants

LITTLE (The Children's Hospital),

RUYS (et al) \$421,175

Pre-clinical validation of a novel implant for bone tissue engineering

MURRAY (Faculty of Pharmacy),

DUNSTAN (et al) \$835,860

Pharmacological development of synthetic analogues of cytochrome P450-mediated omega-3 fatty acid epoxides as novel anti-metastatic agents

National Health and Medical Research Council Grant (NHMRC) Early Career Fellowship

LU \$342,892

Smart synthetic biomaterial for bone tissue regeneration

University of Sydney Widening Participation Grant

AULD \$30,000

2012 Indigenous Australian Engineering Summer School

Industry Funds

SUKKARIEH et al €195,300

European Grant - "Multi-UAV Cooperation International Research Exchange Network" The joint exchange program over 2011-2013 will involve research organizations from Germany, Spain and Australia

SUKKARIEH \$152,000

MLA Project - "New Detection and Classification Algorithms for Mapping Woody Weeds from UAV Data"

SUKKARIEH \$657,000

Qantas Onshore Research: An Algorithm and Software System for Individual Aircraft Fuel Burn

SUKKARIEH \$93,000

Qantas Research- Proof of Concept of New Flight Planning Algorithms

Research Highlights

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Appointments and Promotions

Professor Steve **Armfield** reappointed as Head of School for a second term

Dr Li **Chang** appointed as Lecturer in Materials Engineering, starting in 2012

Dr Matthew Cleary appointed as Lecturer in Mechanical Engineering starting in 2012

Dr Matthew **Dunn** appointed as Lecturer in Mechanical Engineering starting in 2012

Dr Ahmad **Jabbarzadeh** appointed as Lecturer in Mechanical Engineering, starting in 2012

Dr Xiaozhou Liao has been promoted to Associate Professor

Dr Ian Manchester appointed as Senior Lecturer in Aeronautical Engineering, starting in 2012

Dr David Rye has been promoted to Associate Professor

Dr Gareth Vio appointed as Lecturer in Aeronautical Engineering

Dr Stefan Williams has been promoted to Associate Professor

Awards and Honours

Professors Robert **Bilger** and Roger **Tanner** have been elected inaugural fellows of the Australasian Fluid Mechanics Society.

Dr Greg Chamitoff has made a second successful flight to the International Space Station on NASA's shuttle Discovery on 20th May 2011. This will be Discovery's final flight.

Drs Yuhang Chen and Zufu Lu were awarded University International Program Development Funding for further developing their international links.

Professor Yiu-Wing **Mai** was elected an International Fellow of the Royal Academy of Engineering.

Professor Assaad **Masri** and the Research Support team won the Vice Chancellor's award for Excellence.

Dr Steve Scheding has accepted the position of Director of the Rio Tinto Centre for Mine Automation.

Drs Surya **Singh**, Robert **Fitch** and Stefan **Williams** received the Dean's Award for Outstanding Teaching 2011 in the Faculty of Engineering & IT.

Associate Professor Salah **Sukkarieh** has taken over from Hugh Durrant-Whyte as ACFR's Research Director.

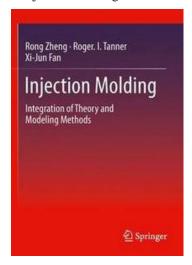
Professor Roger **Tanner** received a silver medal and certificate of recognition for 40 years service to the University.

Ms Annika Van Hummel received the Dean's Award and Mr Lachlan McCalman high commendation for Excellence in Tutoring 2011 for the School of AMME.

Drs Stefan Williams, Surya Singh and Robert Fitch were awarded a \$35k University Teaching Support (STEPS) Grant towards a project for enhancing robotics education.

Drs KC Wong and Dries Verstraete were awarded a \$35k STEPS grant for a 'Global Experiential Design Studio for International Engineering Collaboration'.

Professors Rong **Zheng**, Roger **Tanner** and Xi-Jun **Fan** published a very thorough review of Injection Molding.



Associate Professor Hala **Zreiqat's** research story was aired on Catalyst (ABC) in June 2011.

Aerospace Research

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Research Group

Aerospace Design



Dr Dries Verstraete P: + 61 2 9351 2393 dries.verstraete@sydney.edu.au

- Aircraft design
- Unmanned aerial vehicles
- Micro gas turbines
- Green and renewable propulsion
- Unconventional aircraft configurations
- Hydrogen in aviation
- Propulsion and structures of hypersonic aircraft

Aerospace Engineering



Dr Gareth Vio P: +61 2 9351 2394 gareth.vio@sydney.edu.au

- Non-linear aeroelasticity
- Non-linear vibration
- Non-linear system identification
- Gust response
- Aeroelastic tailoring
- Design of composite structures
- Morphing structures
- Natural selection optimisation

Design Optimisation Research



Dr K Srinivas P: + 61 2 9351 4289 k.srinivas@usyd.edu.au

(Also a member of the Biomedical, Fluid Dynamics Research Groups & Finite Element Analysis Research Center)

- Hierarchical Asynchronous Parallel Evolutionary Algorithms (HAPEAs)
- Robust evolutionary methods for multiobjective and Multidisciplinary Design Optimisation (MDO) in aeronautics.
- Grid free flow-solvers and evolutionary algorithms.
- Adaptive aerofoils/wings design and optimisation using evolutionary algorithms.

Flight Simulation and Control



Dr Peter Gibbens P: +61 2 9351 7350 peter.gibbens@sydney.edu.au

The Variable Stability Flight Simulator (VSFS) is an exclusive project to the University of Sydney, a

national first. In addition to the application of the VSFS to AMME flight mechanics courses, the simulator offers significant potential in other areas. For instance, current post-graduate study is being performed with the aim of producing an avionics course based on the simulator systems. Other post-graduate projects involve guidance and control (landing and flight path) using visual systems simulated with the VSFS.

Smart Structures Research

Professor Liyong Tong P: +61 2 9351 6949 Liyong.tong@sydney.edu.au

(Also a member of <u>Finite</u> <u>Element Analysis Research</u> <u>Center</u>)



Research interests are mainly concerned with modeling behaviors of composite and smart structures. Current research areas and projects include:

- Failure analysis and damage tolerance of adhesive bonded composite joints
- Modeling behavior of 3D reinforced composite materials, including transverse stitching
- Behavior of composite plates and shells
- Smart structures using PZT sensors/actuators, including damage detection and performance control of thinwalled structures

Aerospace Research

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Space Engineering Research



Dr Doug Auld P: +61 2 9351 2336 doug.auld@sydney.edu.au

(Also a member of the <u>Fluid</u> <u>Dynamics Research Group</u>)

The DSMC (Direct Molecular Simulation -

Monte Carlo Method) gas flow simulation technique was pioneered by Emeritus Professor Graeme Bird in this School. The method was originally used for simulation of rarefied gas flow around re-entry vehicles, but has now progressed to the stage of being a useful tool for solving a large range of aerodynamic and aerospace problems such as:

- Simulation of flow separation in near continuum region
- 2. Rankine-Heugonot weak/strong shock reflection solutions
- 3. Nano-Fluid Simulations
- 4. Investigation of stability of low Reynolds number flows



Associate Professor Salah Sukkarieh P: +61 2 9351 8154 salah@acfr.usyd.edu.au

(Also a member of <u>Australian</u> <u>Center for Field Robotics</u> <u>ACFR</u>)

- Planetary Rover Systems
- Navigation in GPS denied environments
- Multi-robot systems for Space
- Multi-satellite navigation and control



Dr Xiaofeng Wu P: +61 2 9036 7053 xiaofeng.wu@sydney.edu.au

- · Small Satellite bus design
- Fault tolerance systems design
- Remote sensing

Unmanned Aerial Vehicle (UAV) Research

Dr KC Wong P: +61 2 9351 2347 kc.wong@sydney.edu.au

Current UAV related research activities include the following:



- Autonomous remote sensing using UAVs;
- Decentralised navigation and control of autonomous flight vehicles;
- Simultaneous localisation and map building for autonomous flight vehicles;
- Design and development of rapid prototype UAVs;
- Wind-tunnel and flight based experimental research in aerodynamics and flight performance;
- Modelling of engine/propeller performance and aircraft stability characteristics;
- High fidelity aircraft model development for simulation based control system validation;
- Trajectory optimisation and autonomous guidance for unmanned aircraft;
- Sensor fusion strategies for state estimation using multiple redundant sensors, including Global Positioning Systems (GPS);
- Using GPS for aircraft attitude determination;
- System identification methods and neural networks for fault detection and reconfiguration;
- Robustness analysis of control laws in the presence of uncertain dynamics and wind gusts;
- Robust nonlinear high-performance manoeuvre tracking for autonomous aircraft;
- Autonomous safe recovery and landing of a UAV;
- Terrain Following for autonomous flight vehicles:
- Integration of available technologies into operational UAV systems;
- Real-time fight control software synthesis for UAVs;
- Design and fabrication of airframe components using advanced composite materials.

Aerospace Research

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Emeritus Professors

Prof Bird, Graeme Prof Steven, Grant

Honorary/ Adjunct Staff

Dr Bates, Peter Dr Chamitoff, Gregory Dr Houghton, Ron Dr Stone, Hugh

Research Fellow

Dr Bryson, Mitchell Dr Islam, Saiful Mohammad

Postdoctoral Fellow

Dr Luo, Quantian

Research Students

Abuhashim, Tariq Anderson, Matthew Armstrong, James Awin, Layth Ali Bai, Xueliang Bartsch, Ronald Brown, Sonya Chung, Jen Jen De Sousa, Manuel Dumble, Steven Gan, Seng Keat Hemakumara, Madu Prasad Ho, Derrick Ho, Ken Po Lam Hung, Calvin Kai-Yuan Kassir, Abdallah Lamburn, Darren Lehmkuehler, Kai Lui, Sin Ting Angela Medagoda, Eran Nguyen, Joseph Richardson, Adam Seiler, Konstantin Martin Vasista, Srinivas Williams, David Wilson, Daniel Briggs Xiao, Size Xu, Zhe Yan, Jun Yoo, Chanyeol Zhang, James Yinye

Research Grants*

Sponsor/ Grant Name	Chief Investigator [other AMME investigators]	Project Title	Duration	Awarded Amount (\$)
CRC Advanced Composite Structures Ltd	Tong, Liyong [Ye, Lin]	Structural Repair and Rehabilitation	Jul 2010 - Jun 2015	318,000
CRC Advanced Composite Structures Ltd	Tong, Liyong [Ye, Lin]	Rapid Assembly Methods	Jul 2010 - Jun 2015	430,500
Australian Research Council/Discovery Projects	Tong, Liyong	Design of compliant structure systems with integrated actuators	Jan 2011 - Dec 2013	290,000
Defence Science and Technology Organisation/Research Support	Verstraete, Dries	Fuel-Cell Unmanned Aircraft System Hardware-in-the-loop Simulation	Jul 2011 - Jun 2012	12,000

^{*} Figures obtained from the Research Office, University of Sydney

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2011 Publications*

Book Chapters

Bai, X, Wu, X 2011, Customized Processor Architecture for Model Predictive Control in Magnetic Actuated Small Satellites, Advanced Electrical and Electronics Engineering (Lecture Notes in Electrical Engineering), Springer, Chennai, India, 2, 71-79

Brown, S, Tong, L, Luo, Q T, Gong, X 2011, Mixed mode energy release rates for bonded composite joints, Composite joints and connections- Principles, modelling and testing, Woodhead Publishing Ltd, UK, 435-462

Tong, L, Luo, Q T 2011, Analytical Approach to Joint Design, Handbook of Adhesion Technology, Springer, Germany, 1, 597-627

Conference Papers

Gibbens, P W, Verstraete, D 2011, Learning aircraft design and flight control system design using flight simulation as a CDIO conduit, 7th International CDIO Conference 2011, Danmarks Tekniske Universitet (DTU), Denmark

Bai, X, Wu, X 2011, A Simulation and Visualization Platform for Fractionated Spacecraft Attitude Control System, 2011 IEEE International Conference on Mechatronics and Automation (IEEE ICMA 2011), IEEE, Beijing, China, 2033-2038

Brooker, G M, Randle, J A G, Attia, M E, Xu, Z, Abuhashim, T, Kassir, A, Chung, J, Sukkarieh, S, Tahir (nee Mariam), N, Dickens, J 2011, First Airborne Trial of a UAV Based Optical Locust Tracker, Australasian Conference on Robotics and Automation (ACRA 2011), ARAA: Australian Robotics & Automation Association, Melbourne, Australia, 1-9

Bryson, M T, Reid, A, Hung, C, Abuhashim, T, Sukkarieh, S 2011, Using unmanned aerial vehicles for mapping, classification and monitoring of invasive weeds, 34th International Symposium for Remote Sensing of the Environment, Unknown, unknown, 1-4

Bryson, M T, Sukkarieh, S 2011, A Comparison of Feature and Pose-Based Mapping using Vision, Inertial and GPS on a UAV, 2011 IEEE/RSJ International Conference on Intelligent Robots and Systems, IEEE/Omnipress, USA, 4256-4262

Chen, X, Wu, X 2011, Design and implementation of model predictive control algorithms for small satellite three-axis stabilization, Information and Automation (ICIA), 2011 IEEE International Conference, IEEE, China, Article number 5949077, 666-671

Chung, J, Sukkarieh, S 2011, High level risk analysis and decision making regarding the prediction of thermal lift locations for an autonomous mars glider, 10th Australian Space Science Conference, National Space Society of Australia Ltd, Australia, 237-248

Gan, J S K, Sukkarieh, S 2011, Multi-UAV Target Search using Explicit Decentralized Gradient-Based Negotiation, IEEE International Conference on Robotics and Automation ICRA 2011, IEEE, USA, CD, 751-756

Hemakumara, P, Sukkarieh, S 2011, Non-Parametric UAV System Identification with Dependent Gaussian Processes, IEEE International Conference on Robotics and Automation ICRA 2011, IEEE, USA, 4435-4441

Ho, D, Wong, K C 2011, Low Thrust to Weight Ratio Manoeuvre of a Bio-inspired Bi-mode UAV, AIAC-14 Fourteenth Australian International Aerospace Congress APISAT 2011, WALDRONSMITHManagement, Melbourne, Australia

Hung, C, Bryson, M T, Sukkarieh, S 2011, Vision-based Shadow-aided Tree Crown Detection and Classification Algorithm using Imagery from an Unmanned Airborne Vehicle, 34th International Symposium for Remote Sensing of the Environment, Unknown, unknown, 1-4

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^{*} Records obtained from the Integrated Research Management Application (IRMA), University of Sydney

- Khodaparast, H, Georgiou, G, Cooper, J, Travaglini, L, Ricci, S, Vio, G, Denner, P 2011, Rapid Prediction of Worst Case Gust Loads, 52nd AIAA/ASME/ASCE/AHS/ASC Structures, Structural Dynamics and Materials Conference, AIAA, USA
- Koster, J, Kraemer, E, Munz, C, Verstraete, D, Wong, K C, Velazco, A 2011, Workforce Development for Global Aircraft Design, ASME 2011 International Mechanical Engineering Congress & Exposition IMECE2011, ASME International USA, USA, IMECE2011-62273-1-IMECE2011-62273-12
- Koster, J, Munz, C, Wong, K C, Velazco, A, Kraemer, E, Verstraete, D 2011, HYPERION UAV: An International Collaboration, 50th AIAA Aerospace Science Meeting, AIAA American Institute of Aeronautics and Astronautics, USA, AIAA-2012-1223
- Koster, J, Serani, E, Velazco, A, Wiley, T, Munz, C, Kurz, H, Kramer, E, Wong, K C, Lehmkuehler, K, Verstraete, D 2011, HYPERION: An International Collaboration, 7th International CDIO Conference 2011, Danmarks Tekniske Universitet (DTU), Denmark
- Lawrance, N R J, Sukkarieh, S 2011, Autonomous soaring for atmospheric exploration of Titan, 10th Australian Space Science Conference, National Space Society of Australia Ltd, Australia, 223-236
- Lawrance, N R J, Sukkarieh, S 2011, Path Planning for Autonomous Soaring Flight in Dynamic Wind Fields, IEEE International Conference on Robotics and Automation ICRA 2011, IEEE, USA, CD, 2499-2505
- Lee, C-J, Townsend, S, Srinivas, K 2011, Optimisation of Stents for Cerebral Aneurysm, Sixth International Conference on Computational Fluid Dynamics (ICCFD 2010), Springer, Germany, 377-382
- Lee, D S, Periaux, J, Srinivas, K, Gonzalez, L, Qin, N, Onate, E 2011, Shock Control Bump Design Optimization on Natural Laminar Aerofoil, Sixth International Conference on Computational Fluid Dynamics (ICCFD 2010), Springer, Germany, 253-259
- Lehmkuehler, K, Wong, K C 2011, Winglet Design for a Fairchild Merlin III using CFD Analysis, AIAC-14 Fourteenth Australian International Aerospace Congress APISAT 2011, WALDRONSMITHManagement, Melbourne, Australia
- Lehmkuehler, K, Wong, K C, Verstraete, D 2011, Hyperion Flying Wing Aircraft Technology, 7th International CDIO Conference 2011, Danmarks Tekniske Universitet (DTU), Denmark
- Reid, A, Ramos, F T, Sukkarieh, S 2011, Multi-Class Classification of Vegetation in Natural Environments Using an Unmanned Aerial System, IEEE International Conference on Robotics and Automation ICRA 2011, IEEE, USA, 2953-2959
- Srinivas, K, Lee, C-J 2011, Optimisation of Stents for Cerebral Aneurysm Application, Eighth International Conference on Flow Dynamics, GCOE Institute of Fluid Science, Tohoku University, Tohoku, Japan, 448-449
- Ullrich, F, Goktogan, A H, Sukkarieh, S 2011, Design Optimization of a Mars Rover's Rocker-Bogie Mechanism using Genetic Algorithms, 10th Australian Space Science Conference, National Space Society of Australia Ltd, Australia, 1, 199-210
- Verstraete, D, Gibbens, P W, Wong, K C 2011, Is a small UAV with extended altitude capabilities feasible?, AIAC-14 Fourteenth Australian International Aerospace Congress APISAT 2011, WALDRONSMITHManagement, Melbourne, Australia
- Verstraete, D, Hendrick, P 2011, Improved Performance Assessment of a Precooled Turbofan for Hypersonic Vehicle Acceleration, 20th ISABE Conference 2011, International Society for Airbreathing Engines, Sweden
- Verstraete, D, Ling, J C, Wong, K C, Armfield, S W 2011, Development of a micro turboprop for high altitude UAV propulsion, 20th ISABE Conference 2011, International Society for Airbreathing Engines, Sweden
- Verstraete, D, Ling, J C, Wong, K C, Armfield, S W 2011, Development of a micro turboprop to extend altitude capabilities of small UAVs, AIAC-14 Fourteenth Australian International Aerospace Congress APISAT 2011, WALDRONSMITHManagement, Melbourne, Australia
- Verstraete, D, Thirifay, F, Hendrick, P 2011, Definition and Optimisation of the Structure of a Hypersonic Aircraft Considering Aero-Elastic Deformations, 4th European Conference for Aerospace Sciences, Torus Press Publishing house, Russia

- Vio, G, Dimitriadis, G 2011, Damping Identification in an Aeroelastic System with Structural Non-Linearities, AIAC-14 Fourteenth Australian International Aerospace Congress APISAT 2011, WALDRONSMITHManagement, Melbourne, Australia
- Vio, G, Miller, S, Cooper, J 2011, Gust Alleviation Device Applied to the Sensorcraft Structure, AIAC-14 Fourteenth Australian International Aerospace Congress APISAT 2011, WALDRONSMITHManagement, Melbourne, Australia
- Wong, K C, Verstraete, D, Lehmkuehler, K, Koster, J, Munz, C, Kraemer, E, Velazco, A 2011, Rapid, International Design and Test of a Hybrid-Powered, Blended-Wing Body Unmanned Aerial Vehicle, 11th AIAA Aviation Technology, Integration and Operation (ATIO) Conference, ASME International USA, USA
- Wu, X, Sam, M, Xiao, S 2011, Targeted processor architecture for embedded real-time control using (delta)-operator, 6th IEEE Conference on Industrial Electronics and Applications ICIEA 2011, IEEE Xplore, United States, 2011, Article number 5975690, 773-778
- Wurgler, S, Sukkarieh, S 2011, Path Planning for a Planetary Rover, 10th Australian Space Science Conference, National Space Society of Australia Ltd, Australia, 1, 211-222
- Xu, Z, Sukkarieh, S 2011, Decentralised Control of Robot Teams with Discrete and Continuous Decision Variables, IEEE International Conference on Robotics and Automation ICRA 2011, IEEE, USA, CD, 4780-4785

Journal Papers

- Brown, S, Tong, L 2011, A localised experimental-numerical technique for determining mixed mode strain energy release rates, Composite Structures, 94(1), 132-142
- Gibbens, P W, Medagoda, E 2011, Efficient Model Predictive Control Algorithm for Aircraft, Journal of Guidance, Control, and Dynamics: devoted to the technology of dynamics and control, 34(6), 1909-1915
- Gu, Y, Tong, L, Tan, P 2011, Surface strain distribution method for delamination detection using piezoelectric actuators and sensors, Journal of Physics: Conference Series, 305(1, Article number 012077), 012077-1-012077-10
- Kang, Z, Wang, R, Tong, L 2011, Combined optimization of bi-material structural layout and voltage distribution for in-plane piezoelectric actuation, Computer Methods in Applied Mechanics and Engineering, 200(13-16), 1467-1478
- Lawrance, N R J, Sukkarieh, S 2011, Autonomous Exploration of a Wind Field with a Gliding Aircraft, Journal of Guidance, Control, and Dynamics: devoted to the technology of dynamics and control, 34(3), 719-733
- Lee, D S, Gonzalez, L, Periaux, J, Srinivas, K, Onate, E 2011, Hybrid-Game Strategies for multi-objective design optimization in engineering, Computers & Fluids, 47(1), 189-204
- Lee, D S, Periaux, J, Gonzalez, L, Srinivas, K, Onate, E 2011, Robust multidisciplinary UAS design optimisation, Structural and Multidisciplinary Optimization, Article in Press
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Yang, L, Tong, L, He, X 2011, Molecular Dynamic Simulation of Sword-Sheath Extraction Behavior in CNT Reinforced Composite, Polymers and Polymer Composites, 19(2-3), 113-118

Biomedical Engineering Research

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Research Group



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Bone cell regulation; Biomaterials; Cancer metastasis to bone; Osteoporosis

Biomaterial synthesis & testing



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Skeletal tissue engineering; Biomaterials and scaffolds development; Arthritis and other musculoskeletal conditions; Bone; Cartilage; Orthopaedics and Dental biomaterials

Computational scaffold tissue engineering; Remodelling for orthopaedics; Dental biomechanics and biomaterials; Computational design for periodic microstructural materials-Optimisation of structural topology

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Biomedical Engineering Research

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$\textbf{Research Grants}^*$

Sponsor/ Grant Name	Chief Investigator [other AMME investigators]	Project Title	Duration	Awarded Amount (\$)
Australian Research Council/Discovery Projects	Li, Qing	Topology Optimisation of Periodic Structures for Stent Design	Jan 2010 - Dec 2012	300,000
Australian Research Council/Discovery Projects	Li, Qing [Zhou, Shiwei]	An Engineering Approach to Design of Metamaterials	Jan 2011 - Dec 2013	210,000
Australian Research Council/Discovery Projects	Li, Wei [Swain, Michael]	Topography optimization of implants for enhancing osseointegration	Jan 2010 - Dec 2014	600,000
National Health and Medical Research Council/Project Grants	Seibel, Markus (Concord Clinical School) [Dunstan, Colin]	The Role of the Osteoblast in Mediating Glucocorticoid-induced Metabolic Dysfunction	Jan 2010 - Dec 2013	788,900
National Health and Medical Research Council/Project Grants	Zreiqat, Hala [Dunstan, Colin]	Novel coatings for orthopaedic implants	Jan 2009 - Dec 2012	430,125
National Health and Medical Research Council/Project Grants	Zreiqat, Hala [Dunstan, Colin]	Harnessing the physiological effects of strontium and zinc to produce novel biomaterials for orthopaedic applications	Jan 2010 - Dec 2012	539,500
Australian Research Council/Linkage Projects	Zreiqat, Hala	Scaffolds for bone tissue regeneration and use in orthopaedic applications	Jan 2009 - Dec 2012	504,000
Australian Orthopaedic Association Research Foundation	Zreiqat, Hala	Novel coatings for orthopaedic application	Jan – Dec 2011	60,000
National Health and Medical Research Council/Career Awards: Research Fellowships	Zreiqat, Hala	Senior Research Fellowship A	Jan 2011 - Dec 2015	570,640

^{*} Figures obtained from the Research Office, University of Sydney

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2011 Publications[†]

Conference Papers

Tammareddi, S, Li, Q 2011, An inverse approach to shape optimization for design of cardiovascular stents, 9th World Congress on Structural and Multidisciplinary Optimization, CD Proceedings, Shizuoka, Japan, 381_1(page 1)-381_1(page 10)

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Lu, Z., Roohani-Esfahani, S, Kwok, P C, Zreiqat, H 2011, Osteoblasts on Rod Shaped Hydroxyapatite Nanoparticles Incorporated PCL Film Provide an Optimal Osteogenic Niche for Stem Cell Differentiation, Tissue Engineering. Part A: Tissue Engineering, 17(11/12), 1651-1661

 $^{^{\}dagger}$ Records obtained from the Integrated Research Management Application (IRMA), University of Sydney

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Centre for Advanced Materials Technology (CAMT) Back to Index

The Centre for Advanced Materials Technology (CAMT) was established in 1989 at the University of Sydney, Australia. The aims of CAMT are to conduct high quality fundamental research in materials science and technology and to promote collaboration with industry in the design, engineering, development and manufacturing technology of advanced materials, which can give a competitive edge to new products and processes. It has a widely recognised international and national reputation for high quality research, equipped with state-of-the-art facilities of processing, characterisation and mechanical testing.

CAMT carries out investigations and R&D projects for industry. Technology transfer to industry occurs through workshops, short courses and seminars. The Centre has an international exchange program and supports postgraduate students in advanced materials technology. CAMT is one of partners of CRC-ACS (Cooperative Research Centre for Advanced Composite Structures).

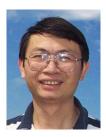
Research Group



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Materials science and engineering; advanced fibre composites; polymer blends; forming, joining and welding; biomimetics, biomaterials and

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Materials science; property profile of composite materials (fatigue and fracture, residual strength, long-term properties, structureproperty relationship and microscopic characterisation); interlaminar stresses and delamination in composite laminates; manufacturing techniques and processing performance models for high polymer composites; composites design; rehabilitation of infrastructure using fibre composites, polymer composite tribology and epoxy adhesive joints for engineering structures

Centre for Advanced Materials Technology (CAMT)

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(<u>Biomedical Research Group</u>)

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Research Grants*

Sponsor/ Grant Name	Chief Investigator [other AMME investigators]	Project Title	Duration	Awarded Amount (\$)
Group of Eight/Germany Joint Research Co-operation Scheme	Chang, Li [Ye, Lin]	Nanomechanical characterization of the ultra-thin transfer film in polymer tribology	Jan 2011 - Dec 2012	20,000
Australian Research Council/Linkage Projects	Liao, Xiaozhou	In-situ transmission electron microscopy nanoindentation investigation of advanced structural metallic materials	Jan 2010 - Dec 2012	301,338
Australian Research Council/Future Fellowships	Liu, Hong	Fatigue Life Prediction of Nano- filler Modified Composites	Nov 2009 - Dec 2013	624,300
Australian Research Council/Discovery Projects	Wang, Yanbo	Effects of grain size on the deformation mechanisms and mechanical properties of Gum Metals (Ti alloys)	Jan 2011 - Dec 2013	255,000
DVC Research/Postdoctoral Research Fellowship Scheme	Yang, Chuncheng	Development of high-efficiency thermoelectric materials by nanostructuring bulk silicon for power regeneration applications	Jan 2011 - Jan 2014	352,789
Australian Research Council/Discovery Projects	Ye, Lin	Fibrous fabric with directional transplanar transport properties for moisture and water	Jan 2011 - Dec 2013	360,000
CRC Advanced Composite Structures Ltd	Tong, Liyong [Ye, Lin]	Structural Repair and Rehabilitation	Jul 2010 - Jun 2015	318,000
CRC Advanced Composite Structures Ltd	Tong, Liyong [Ye, Lin]	Rapid Assembly Methods	Jul 2010 - Jun 2015	430,500

^{*} Figures obtained from the Research Office, University of Sydney

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2011 Publications[†]

Book Chapters

Friedrich, K, Chang, L, Haupert, F 2011, Current and future applications of polymer composites in the field of tribology, Composite Materials: A Vision for the Future, Springer, London, UK, 129-167

Xie, X, Liu, S, Du, F, Mai, Y 2011, Polymer-magnesium hydroxide nanocomposites by emulsion polymerization, Polymer Nanocomposites by Emulsion and Suspension Polymerization, RSC Publishing, Cambridge, UK, 180-197

Yang, Y, Xie, X, Mai, Y 2011, Functionalization of carbon nanotubes for polymer nanocomposites, Polymer-carbon nanotube composites (Preparation, properties and applications), Woodhead Publishing Limited, UK, 55-91

Conference Papers

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Chang, L, Friedrich, K 2011, Develop wear-resistant polymeric composites by using nanoparticles, 18th International Conference on Composite Materials (ICCM18), The Korean Society for Composite Materials, Korea, Article No. T16 AF0629, 1-6

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Mustapha, S, Wang, D, Ye, L 2011, Debonding detection in CF/EP sandwich structures using active sensor network, 18th International Conference on Composite Materials (ICCM18), The Korean Society for Composite Materials, Korea, Article No. T07-4 AF1450

Wang, D, Lu, Y, Tang, Y, Ye, L 2011, Monitoring of delamination onset in composite laminates using lamb signals, 18th International Conference on Composite Materials (ICCM18), The Korean Society for Composite Materials, Korea, Article No. W35-2 AF1260

Journal Papers

Baji, A, Mai, Y, Du, X S, Wong, S 2011, Improved Tensile Strength and Ferroelectric Phase Content of Self-Assembled Polyvinylidene Fluoride Fiber Yarns, Macromolecular Materials & Engineering, 296, Article in Press

Baji, A, Mai, Y, Li, Q, Liu, Y 2011, Electrospinning induced ferroelectricity in poly(vinylidene fluoride) fibers, Nanoscale, 3(8), 3068-3071

Baji, A, Mai, Y, Li, Q, Liu, Y 2011, Nanoscale investigation of ferroelectric properties in electrospun barium titanate/polyvinylidene fluoride composite fibers using piezoresponse force microscopy, Composites Science and Technology, 71(11), 1435-1440

Baji, A, Mai, Y, Li, Q, Wong, S, Liu, Y, Yao, Q 2011, One-dimensional multiferroic bismuth ferrite fibers obtained by electrospinning techniques, Nanotechnology, 22(23), 235702-1-235702-6

Baji, A, Mai, Y, Wong, S 2011, Effect of fiber diameter on the deformation behavior of self-assembled carbon nanotube reinforced electrospun Polyamide 6,6 fibers, Materials Science and Engineering A: Structural Materials: Properties, Microstructures and Processing, 528(21), 6565-6572

Bal, K, Fan, J, Sarkar, M, Ye, L 2011, Differential spontaneous capillary flow through heterogeneous porous media, International Journal of Heat and Mass Transfer, 54(13-14), 3096-3099

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[†]Records obtained from the Integrated Research Management Application (IRMA), University of Sydney

- Ballarre, J, Seltzer, R, Mendoza, E, Orellano, J, Mai, Y, Garcia, C, Cere, S 2011, Morphologic and nanomechanical characterization of bone tissue growth around bioactive sol-gel coatings containing wollastonite particles applied on stainless steel implants, Materials Science and Engineering C: Materials for Biological Applications, 31(3), 545-552
- Cao, Y, Wang, Y, Figueiredo, R, Chang, L, Liao, X, Kawasaki, M, Zheng, W, Ringer, S P, Langdon, T, Zhu, Y 2011, Three-dimensional shear-strain patterns induced by high-pressure torsion and their impact on hardness evolution, Acta Materialia, 59(10), 3903-3914
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- Feng, Q, Shen, X, Yang, J, Fu, S, Mai, Y, Friedrich, K 2011, Synthesis of epoxy composites with high carbon nanotube loading and effects of tubular and wavy morphology on composite strength and modulus, Polymer, 52(26), 6037-6045
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- Liu, X, Yang, Q, He, X, Mai, Y 2011, Molecular mechanics modeling of deformation and failure of super carbon nanotube networks, Nanotechnology, 22(47), 1 (Article 475701)-11
- Lu, X, Lu, M, Zhou, L, Su, Z, Cheng, L, Ye, L, Meng, G 2011, Evaluation of welding damage in welded tubular steel structures using guided waves and a probability-based imaging approach, Smart Materials and Structures, 20(1), 015018-1-015018-15
- Miao, Xiaoting, Wang, D, Ye, L, Lu, Y, Li, F, Meng, G 2011, Identification of Dual Notches Based on Time-Reversal Lamb Waves and a Damage Diagnostic Imaging Algorithm, Journal of Intelligent Material Systems and Structures, 22(17), 1983-1992
- Ni, S, Sha, G, Wang, Y, Liao, X, Alhajeri, S, Li, H, Zhu, Y, Langdon, T, Ringer, S P 2011, Elemental redistribution in a nanocrystalline Ni-Fe alloy induced by high-pressure torsion, Materials Science and Engineering A: Structural Materials: Properties, Microstructures and Processing, 528(25-26), 7500-7505
- Ni, S, Wang, Y, Liao, X, Alhajeri, S, Li, H, Ringer, S P, Langdon, T, Zhu, Y 2011, Grain size effect on deformation twinning and de-twinning in a nanocrystalline Ni-Fe alloy, Materials Science Forum, 667-669, 181-186

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- Ni, S, Wang, Y, Liao, X, Alhajeri, S, Li, H, Zhao, Y, Lavernia, E, Ringer, S P, Langdon, T, Zhu, Y 2011, Strain hardening and softening in a nanocrystalline NiFe alloy induced by severe plastic deformation, Materials Science and Engineering A: Structural Materials: Properties, Microstructures and Processing, 528(9), 3398-3403
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- Seltzer, R, Cisilino, A, Frontini, P, Mai, Y 2011, Determination of the Drucker-Prager parameters of polymers exhibiting pressure-sensitive plastic behaviour by depth-sensing indentation, International Journal of Mechanical Sciences, 53(6), 471-478
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- Zhou, C, Liu, Z, Yan, Y, Du, X S, Mai, Y, Ringer, S P 2011, Electro-synthesis of novel nanostructured PEDOT films and their application as catalyst support, Nanoscale Research Letters, 6, 364-1-364-6
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Finite Element Analysis Research Center

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The Finite Element Analysis Research Center was (FEARC) has been a part of the School of Aerospace, Mechanical and Mechatronic Engineering at The University of Sydney since July 1992. The center's primary aim is to serve as a national focus for research in Finite Element Analysis.

Research Group

The academic members of the center include:

Director

Prof Tong, Liyong (<u>Aerospace Research Group</u>)

Emeritus Professors

Prof Steven, Grant

Research Fellows

A/Prof Qing Li

Dr Wei Li

Dr K Srinivas

(Biomedical Research Group)

(Biomedical Research Group)

(Aerospace Research Group)

The staff and associates of FEARC are very active in a large range of topics, samples of which are given below:

- FE analysis for the draping of cloth structures for aircraft or garment.
- Error estimation in dynamic and buckling FEA analysis.
- FE Modelling of Piezo-elastodynamics for the control of very flexible structures.
- Evolutionary structural optimisation.
- FE Modelling and design optimisation of dental structures.
- FE modelling of biomechanical processes such as spinal manipulation or hip implants or prosthesis.
- Crack tracking algorithms for fracture mechanics.
- FEA modelling of acoustics and fluid/structure interaction.

Rheology Research

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Research Group



Professor Roger Tanner P: + 61 2 9351 7153 roger.tanner@sydney.edu.au

- Rheology
- Polymer processing
- Computational mechanics

Dr Ahmad Jabbarzadeh P: + 61 2 9351 2344

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- Nano-rheology and nanotribology
- Boundary condition and wall slip at the fluid-solid interface
- Characterizing material properties by molecular level simulations
- Novel 3D nano-structures, the origin of high rigidity for ultra-thin liquid films
- Low friction states of films only a few nanometer thick
- Linking material properties and molecular architecture en route to design of customized purpose materials
- Using molecular simulations to study crystallization of polymers

Honorary/ Adjunct Staff

Prof Fan, Xijun A/Prof Zheng, Rong

Postdoctoral Fellows

Dr Dai, Shao Cong Dr Kittipoomwong, Prakorn David Dr Qi, Fuzhong

Research Associates

Bertevas, Erwan Dr Lee Wo, Duane Dr Uthayakumaran, Surjani

Research Students

Ramin, Leyla

Research Grants*

Sponsor/ Grant Name	Chief Investigator [other AMME investigators]	Project Title	Duration	Awarded Amount (\$)
Australian Research Council/Discovery Projects	Jabbarzadeh, Ahmad	Multiscale modelling of flexible fibrous suspensions under flow	Jan 2009 – Dec 2011	360,000
Australian Research Council/Discovery Projects	Tanner, Roger	Modelling soft viscoelastic solids	Jane 2010 - Dec 2012	400,000
Australian Research Council/Discovery Projects	Tanner, Roger [Fan, Xijun]	Rheology of suspensions with viscoelastic matrices	Jan 2011 - Dec 2013	360,000

^{*} Figures obtained from the Research Office, University of Sydney

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2011 Publications[†]

Book

Zheng, R, Tanner, R I, Fan, X 2011, Injection Molding: Integration of Theory and Modeling Methods, Springer, Heidelberg Dordrecht London New York

Book Chapter

Ramin, L, Jabbarzadeh-Khoei, A 2011, Odd-Even Effect in Self Assembly and Phase Transition of Alkanethiols Monolayers (SAMs) on Au (111) Surfaces, Nanotech 2011: Technical Proceedings of the 2011 NSTI Nanotechnology Conference and Expo, CRC Press, Austin, Texas, U.S.A, 1, 476-479

Conference Papers

Jabbarzadeh-Khoei, A 2011, Detecting local molecular order and stresses in flow induced polymer crystallization, 7th International Symposium on Molecular Mobility and Order in Polymer Systems, Russian Academy of Sciences, Russia, O-70

Ramin, L, Jabbarzadeh-Khoei, A 2011, Odd-Even effects on tribology of self assembled monolayers, ASME/STLE 2011 International Joint Tribology Conference (IJTC2011), ASME, Los Angeles, USA, 61150-1-61150-3

Journal Papers

Dai, S C, Qi, F, Tanner, R I 2011, Interpreting shear creep data for bread dough using a damage function model, Applied Rheology (Fliessverhalten steuern), 21(4), 45070-1-45070-6

Housiadas, K, Tanner, R I 2011, Perturbation solution for the viscoelastic 3D flow around a rigid sphere subject to simple shear, Physics of Fluids, 23, 083101-1-083101-20

Housiadas, K, Tanner, R I 2011, The angular velocity of a freely rotating sphere in a weakly viscoelastic matrix fluid, Physics of Fluids, 23(5), 051702-1-051702-4

Jabbarzadeh-Khoei, A, Tanner, R I 2011, Thin lubricant films confined between crystalline surfaces: Gold versus mica, Tribology International, 44(6), 711-719

Kittipoomwong, P, Jabbarzadeh-Khoei, A 2011, Effect of fibre curvature on the rheology of particulate suspensions, Journal of Non-Newtonian Fluid Mechanics, 166(23-24), 1347-1355

Qi, F, Tanner, R I 2011, Random close packing and relative viscosity of multimodal suspensions, Rheologica Acta, Article in Press

Qi, F, Tanner, R I 2011, Relative viscosity of bimodal suspensions, Korea - Australia Rheology Journal, 23(2), 105-111

Ramin, L, Jabbarzadeh-Khoei, A 2011, Odd-even effects on the structure, stability, and phase transition of alkanethiol self-assembled monolayers, Langmuir, 27(16), 9748-9759

Tanner, R I, Uthayakumaran, S, Qi, F, Dai, S C 2011, A suspension model of the linear viscoelasticity of gluten doughs, Journal of Cereal Science, 54(2), 224-228

 $^{^{\}dagger}$ Records obtained from the Integrated Research Management Application (IRMA), University of Sydney

Australian Centre for Field Robotics (ACFR)

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The Australian Centre for Field Robotics (ACFR) is based in the School of Aerospace, Mechanical and Mechatronic Engineering at The University of Sydney, and is dedicated to the research, development, application and dissemination of field robotics principles.

The group has substantial experimental facilities including three laboratories and a field test site, a range of experimental and production vehicles, industry-quality mechanical and electrical design and fabrication facilities, and employs the latest in embedded computing, sensing and control technologies.

The ACFR is now the largest robotics and automation research group in Australia and is also one of the largest of its kind in the world.

Research and Industry Partnerships

- ARC Centre of Excellence for Autonomous Systems (CAS)
- CRC Mining Australia
- Rio Tinto Centre for Mine Automation
- Centre of Expertise in Defence Autonomous & Uninhabited Vehicle Systems, DSTO, Australian Government
- Centre for Autonomous Aerospace Systems
- Centre for Social Robotics
- IMOS AUV Facility
- Academic Capability Partner BAE Systems

Key Research Areas

The Fundamental Research Program focuses on enabling technologies in four key areas. These areas draw together common themes and research priorities from the applied research program with the goal of supporting long-term developments across the whole field robotics area.

- Perception, sensing, representations of information, the modelling and management of uncertainty, data fusion and perceptual interpretation.
- Control, of individual micro and macro machines, of heterogeneous groups of platforms and sensors, and of contact and interaction with the environment and each other.
- Learning, supervised and unsupervised learning in unstructured and dynamic environments, multi-agent learning, pattern recognition and concept formation.
- Systems, design and optimisation of "systems of systems", modelling and management of complexity, large scale systems theory, and modelling of information flow.

These themes define the science of field robotics and represent the main focus of ACFR. The projects ensure that the many threads of the fundamental research programs are brought together and that a bridge exists to further commercial development of research results.

Australian Centre for Field Robotics (ACFR)

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Research Group



Professor Hugh Durrant-Whyte P: + 61 2 9351 5583 h.durrant-whyte@cas.edu.au

 Demonstration of non-Gaussian Decentralised Data Fusion (DDF) concepts on multiple

heterogeneous autonomous systems

- To develop weed detection methodologies and weed destruction methods that can be implemented in an autonomous nonherbicidal weeding system
- High-speed on-road autonomous ground vehicle manoeuvres
- Unmanned agricultural operations



Professor Eduardo Nebot P: + 61 2 9351 2343 eduardo.nebot@sydney.edu.au

Perception research



Associate Professor Salah Sukkarieh P: +61 2 9351 8154 salah@acfr.usyd.edu.au

- UAV systems for agriculture and ecosystem management
- Decentralised navigation and control of UAVs
- Simultaneous localisation and map building for UAVs



Dr Graham Brooker P: + 61 2 9351 4023 gbrooker@acfr.usyd.edu.au

Sensor research



Associate Professor David Rye P: + 61 2 9351 2286

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Systems Research (Perception and Control)

- Fish-Bird (an interactive kinetic artwork in which two robots in the form of wheelchairs communicate with their audience, and with each other, through movement and written text)
- CAS Outdoor Research Demonstrator (generic UGV platform for testing control, perception and learning algorithms)



Dr Steve Scheding P: +61 2 9351 8929 s.scheding@cas.edu.au

Perception Research

- Fish-Bird
- CAS Outdoor Research Demonstrator
- Investigation and development of appropriate multi-sensor systems to monitor/estimate foodstuff temperature, mass and moisture content, and foodstuff chemical/protein changes)



Associate Professor Stefan Williams P: + 61 2 9351 8152

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- Long-term operation of a robotic ground vehicle in an outdoor environment
- Undersea vehicles
- Fish-Bird

Robotics Research

Australian Centre for Field Robotics (ACFR)

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Research Fellows/ Associates

Dr Allen, Thomas Dr Douillard, Bertrand Dr Elinas, Pantelis Dr Fitch, Robert Dr Göktoğan, Ali Prof Hatherly, Peter Dr Hill, Andrew Dr Johnson, David Dr Johnson-Roberson, Matthew Lawrance, Nicholas Dr Melkumyan, Arman Dr Monteiro, Sildomar Dr Murphy, Richard Dr Nieto, Juan Mr Nourani-Vatani, Navid Mr Orchansky, David Dr Peynot, Thierry Dr Ramos, Fabio Reid, Alistair Dr Underwood, James Dr Vasudevan, Shrihari Dr Velonaki, Mari

Administrative Staff

Dr Worrall, Stewart

Zhou, Hang (Cathy)

Hunter-Smith, Lisa Olip, Ruth Sawtell, Olga Wang, Christy (Finance)

Technical Staff

Attia, Muhammad Esa Blekhman, Alexander Calleija, Mark Chan, Victor Chen, Quanjun (Jerry) Durrant, Andrew Geier, Matthew Goyal, Abhinav Hale, Tim Hennessy, Ross Lal, Ritesh Lees, Christian Leung, Raymond Lowe, Alex Maclean, Andrew Martinez, Javier McCouat, Nicholas Merry, Laura Miller, Tim Nguyen, Dai Bang Ralph, Daniel Randle, Jeremy Vitjuk, Ivan Vlaskine, Vsevolod Wishart, Stuart Wohlleber, Cedric Wright, James Zigman, John

Research Students

Abuhashim, Tariq
Agamennoni, Gabriel
Ahsan, Nasir
Awin, Layth
Ball, Adrian
Barkby, Stephen
Bender, Asher
Bongiorno, Daniel
Brown, Iain
Brunner, Christopher
Castro, Marcos
Chung, Jen Jen
Clarke, Bryan
Dansereau, Don
DeDeuge, Mark

Friedman, Ariell Gan. Seng Keat (Jason) Guizilini, Vitor Hemakumara, Madu Prasad Hernandez, Andres Ho, Ken Hung, Calvin Innes, Christopher Jasinski, Tomasz Kassir, Abdallah Kuo, Victor Lee, Seong Ho Lui, Sin Ting (Angela) Lupton, Todd Maeda, Guilherme McAllister, Rowan McCalman, Lachlan Medagoda, Lashika Mikl, Joanne Morton, Peter Nguyen, Joseph O'Callaghan, Simon **Quadros**, Alastair Romero, Victor Adolfo Schneider, Sven Seiler, Konstantin Shan, Mao Silvera, David Silversides, Katie Steinberg, Daniel Tahir, Nazifa Toohey, Lachlan Valdes, Bulmaro Van de Ven, Joop Vial, John

Wilson, Daniel

Yoo, Chanyeol

Zubizarreta, Jose Francisco

Xu, Zhe

Robotics Research

Australian Centre for Field Robotics (ACFR)

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Research Grants*

Sponsor/ Grant Name	Chief Investigator	Project Title	Duration	Awarded Amount (\$)
Australian Research Council/Discovery Projects	Douillard, Bertrand	Multi-scale recognition: generating meaning from multi-resolution data	Jun 2011 - Jun 2014	255,000
Australian Research Council/Federation Fellowships	Durrant-Whyte, Hugh	Data Fusion and Perception in Autonomous Networks	Oct 2007 - Oct 2012	1,606,210
Technological Resources P/L	Durrant-Whyte, Hugh	Rio Tinto Centre for Mine Automation	Aug 2007 - July 2014	34,649,940
BAE Systems	Durrant-Whyte, Hugh	Agreement for CIMS	Mar 2010 - Feb 2012	900,000
CRC Mining	Nebot, Eduardo	CRC	Jan - Dec 2011	583,355
AOARD	Peynot, Thierry	Sensor Data Integrity and Mitigation of Perceptual Failures	Oct 2010 - May 2013	261,993
Australian Research Council QEII	Pizarro, Oscar	Cost-effective autonomous systems for large scale monitoring of marine protected areas	Jan 2010 - Dec 2014	798,000
Meat & Livestock Australia Limited	Sukkarieh, Salah	New Detection and Classification Algorithms for Mapping Woody Weeds from UAV Data	Jun 2011 - Aug 2012	152,813
University of New South Wales/Shared Research Support	Sukkarieh, Salah	Pathways to space: Empowering the internet generation	Jun 2010 - Mar 2013	300,196
Qantas	Sukkarieh, Salah	Proof of Concept of New Flight Planning Algorithms	2011	93,000
Qantas	Sukkarieh, Salah	An algorithm and software system for individual aircraft fuel burn characterisation	Oct 2011 - Feb 2013	656,830
Republic of Korea Agency for Defence Development	Underwood, James	Multi-Modal Adaptive Simultaneous Localisation and Mapping (SLAM) for Unmanned Ground Vehicles (UGVs) in complex urban and unstructured environments	May 2011 - Oct 2013	420,000
Australian Research Council Future Science	Williams, Stefan	Machine Assisted, Multi-scale Spatial and Temporal Observation and Modeling of Marine Benthic Habitats	Jul 2010 - Jun 2013	278,400
Science and Industry Endowment Fund	Williams, Stefan	John Stocker Postdoctoral Fellowships	Oct 2011- Oct 2014	276,000
University of Western Australia administering funds from ENI Australia Ltd	Williams, Stefan	South East Asia (SEA) node of the Scientific & Environmental ROV Programme using Existing Industrial Technology (SERPENT)	Mar 2011 - Mar 2012	13,400
NCRIS	Williams, Stefan	Use of Autonomous Underwater Vehicle at IMOS AUV facility	Jul 2008 - Jun 2013	1,582,499
Australian Research Council/Linkage Projects	Williams, Stefan	Autonomous repeatable surveys for long term monitoring of marine habitats	Jan 2009 - Dec 2011	320,000
Australian Research Council/Linkage Projects	Williams, Stefan	Supervised autonomy for autonomous underwater vehicles (AUVs) using limited bandwidth communication channels	Jul 2011- Jun 2014	245,538
Thales	Williams, Stefan	Autonomous repeatable surveys for long term monitoring of marine habitats	Jan - Dec 2011	54,545

^{*} Figures obtained from Finance Office, ACFR, University of Sydney

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Australian Centre for Field Robotics (ACFR)

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2011 Publications[†]

Conference Papers

Agamennoni, G, Nieto, J I, Nebot, E M 2011, A Bayesian approach for driving behavior inference, 2011 IEEE Intelligent Vehicles Symposium, OmniPress, Baden-Baden, Germany, 595-600

Agamennoni, G, Nieto, J I, Nebot, E M 2011, An Outlier-Robust Kalman Filter, IEEE International Conference on Robotics and Automation ICRA 2011, IEEE, USA, 1551-1558

Allen, T L, Scheding, S J 2011, The Time-Optimal Planning and Execution Problem, IEEE International Conference on Robotics and Automation ICRA 2011, IEEE, USA, 5608-5614

Bailey, T A, Bryson, M T, Mu, H, Vial, J, McCalman, L, Durrant-Whyte, H F 2011, Decentralised Cooperative Localisation for Heterogeneous Teams of Mobile Robots, IEEE International Conference on Robotics and Automation ICRA 2011, IEEE, USA, 2859-2865

Ball, A, Rye, D C, Ramos, F T, Velonaki, M 2011, A Comparison of Unsupervised Learning Algorithms for Gesture Clustering, 6th ACM/IEEE International Conference on Human-Robot Interaction (HRI 2011), Unknown, unknown, 111-112

Barkby, S A, Williams, S B, Pizarro, O R, Jakuba, M 2011, Bathymetric SLAM with No Map Overlap using Gaussian Processes, 2011 IEEE/RSJ International Conference on Intelligent Robots and Systems, IEEE/Omnipress, USA, 1242-1248

Bastos, G, Souza, L, Ramos, F T, Ribeiro, C 2011, A Single-dependent Agent Approach for Stochastic Time-Dependent Truck Dispatching in Open-pit Mining, 14th International IEEE Annual Conference on Intelligent Transportation Systems (ITSC 2011), OmniPress, Washington, DC, USA, 1057-1062

Beall, C, Dellaert, F, Mahon, I J, Williams, S B 2011, Bundle adjustment in large-scale 3D reconstructions based on underwater robotic surveys, OCEANS 2011 Santander Spain, IEEE, unknown, 1-6

Brooker, G M, Randle, J A G, Attia, M E, Xu, Z, Abuhashim, T, Kassir, A, Chung, J, Sukkarieh, S, Tahir (nee Mariam), N, Dickens, J 2011, First Airborne Trial of a UAV Based Optical Locust Tracker, Australasian Conference on Robotics and Automation (ACRA 2011), ARAA: Australian Robotics & Automation Association, Melbourne, Australia, 1-9

Brunner, C J, Peynot, T, Vidal Calleja, T 2011, Combining multiple sensor modalities for a localisation robust to smoke, 2011 IEEE/RSJ International Conference on Intelligent Robots and Systems, IEEE/Omnipress, USA, 2489-2496

Bryson, M T, Reid, A, Hung, C, Abuhashim, T, Sukkarieh, S 2011, Using unmanned aerial vehicles for mapping, classification and monitoring of invasive weeds, 34th International Symposium for Remote Sensing of the Environment, Unknown, unknown, 1-4

Bryson, M T, Sukkarieh, S 2011, A Comparison of Feature and Pose-Based Mapping using Vision, Inertial and GPS on a UAV, 2011 IEEE/RSJ International Conference on Intelligent Robots and Systems, IEEE/Omnipress, USA, 4256-4262

Cappelli, J, Goktogan, A H 2011, A 3D dynamics simulation model of CliffRider: The abseiling face inspection robot, Simulation Conference and Exhibition, SimTecT'11, Simulation Australia, Adelaide, Australia, 8-13

Cappelli, J, Goktogan, A H 2011, Analysis of control strategies and dynamic behaviour of CliffRider: The single wheeled abseiling face inspection robot, 37th Annual Conference of the IEEE Industrial Electronics Society, IEEE Industrial Electronics Society, Melbourne, Australia, 21-26

Cappelli, J, Goktogan, A H 2011, Design of a novel climbing robot - cliffrider: the abseiling face inspection robot, 14th International Conference on Climbing and Walking Robots, World Scientific Books, Paris, France, 423-430

[†] Records obtained from the Integrated Research Management Application (IRMA), University of Sydney

Chung, J, Sukkarieh, S 2011, High level risk analysis and decision making regarding the prediction of thermal lift locations for an autonomous mars glider, 10th Australian Space Science Conference, National Space Society of Australia Ltd, Australia, 237-248

Dansereau, D, Mahon, I J, Pizarro, O R, Williams, S B 2011, Plenoptic flow: Closed-Form VisualOdometry for Light Field Cameras, 2011 IEEE/RSJ International Conference on Intelligent Robots and Systems, IEEE/Omnipress, USA, 4455-4462

Dansereau, D, Williams, S B 2011, Seabed Modeling and Distractor Extraction for Mobile AUVs Using Light Field Filtering, IEEE International Conference on Robotics and Automation ICRA 2011, IEEE, USA, 1634-1639

Douillard, B, Underwood, J P, Kuntz, N, Vlaskine, V, Quadros, A, Morton, P, Frenkel, A 2011, On the Segmentation of 3D LIDAR Point Clouds, IEEE International Conference on Robotics and Automation ICRA 2011, IEEE, USA, 2798-2805

Ferguson, D.S., Elinas, P 2011, A Markov decision process model for strategic decision making in sailboat racing, 24th Canadian Conference on Artificial Intelligence, Springer, unknown, 6657, 110-121

Friedman, A, Pizarro, O R, Williams, S B 2011, Interpretation of benthic stereo imagery using 2D and 3D features in an active learning framework, GeoHab 2011, Unknown, unknown, 37-37

Friedman, A, Steinberg, D, Pizarro, O R, Williams, S B 2011, Active learning using a Variational Dirichlet Process model for pre-clustering and classification of underwater stereo imagery, 2011 IEEE/RSJ International Conference on Intelligent Robots and Systems, IEEE/Omnipress, USA, 1533-1539

Gan, J S K, Sukkarieh, S 2011, Multi-UAV Target Search using Explicit Decentralized Gradient-Based Negotiation, IEEE International Conference on Robotics and Automation ICRA 2011, IEEE, USA, CD, 751-756

Guizilini, V C, Ramos, F T 2011, Visual Odometry Learning for Unmanned Aerial Vehicles, IEEE International Conference on Robotics and Automation ICRA 2011, IEEE, USA, CD, 6213-6220

Hemakumara, P, Sukkarieh, S 2011, Non-Parametric UAV System Identification with Dependent Gaussian Processes, IEEE International Conference on Robotics and Automation ICRA 2011, IEEE, USA, 4435-4441

Hernandez, G A, Nieto, J I, Bailey, T A, Nebot, E M 2011, Probabilistic Road Geometry Estimation Using a Millimetre-Wave Radar, 2011 IEEE/RSJ International Conference on Intelligent Robots and Systems, IEEE/Omnipress, USA, 4601-4607

Hung, C, Bryson, M T, Sukkarieh, S 2011, Vision-based Shadow-aided Tree Crown Detection and Classification Algorithm using Imagery from an Unmanned Airborne Vehicle, 34th International Symposium for Remote Sensing of the Environment, Unknown, unknown, 1-4

Innes, C, Nettleton, E W, Melkumyan, A 2011, A System for Ore Tracking in Autonomous Mining, 35th APCOM Symposium 2011, The Australasian Institute of Mining and Metallurgy, Carlton, Victoria, 719-733

Innes, C, Nettleton, E W, Melkumyan, A 2011, Estimation and tracking of excavated material in mining, 14th International Conference on Information Fusion, International Society on Information Fusion - ISIF, Chicago, USA, 1631-1638

Jakuba, M, Steinberg, D, Kinsey, J, Yoerger, D, Camilli, R, Pizarro, O R, Williams, S B 2011, Toward Automatic Classification of Chemical Sensor Data from Autonomous Underwater Vehicles, 2011 IEEE/RSJ International Conference on Intelligent Robots and Systems, IEEE/Omnipress, USA, 4722-4727

Johnson, D G, Calleija, MS, Brooker, G M, Nettleton, E W 2011, Development of a dual-mirror-scan elevation-monopulse antenna system, 2011 8th European Radar Conference, Horizon House Publications, United Kingdom, 281-284

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Combustion

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Research Group



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Lifted flames; Incineration of halons and CFC's; Chemical inhibition of halons in flames; Experimental investigations of methanol and ethanol flames; PDF-Monte Carlo calculations of turbulent non-premixed flames

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Postdoctoral Fellows

Dr Juddoo, Mrinal Dr Kourmatzis, Agisilaos Dr Nakul, Vinayaka Prasad Dr Starner, Sten

Research Students

Al-Harbi, Ahmed Badra, Jihad O'Loughlin, William Meares, Shaun Pham, Xuan Phuong Sivapalan, Kumaresan

Research Grants*

Sponsor/ Grant Name	Chief Investigator [other AMME investigators]	Project Title	Duration	Awarded Amount (\$)
Australian Research Council/Discovery Projects	Masri, Assaad [Bilger, Robert]	Strongly Transient Processes in Turbulent Combustion	Jan 2010 - Dec 2012	653,555
Australian Research Council/Discovery Projects	Masri, Assaad	Towards a Unified View of Clean Turbulent Combustion	Jan 2011 - Dec 2015	1,250,000
Australian Research Council/Linkage, Infrastructure, Equipment and Facilities (LIEF)	Masri, Assaad	Multi-dimensional, high-speed laser imaging facility for fluids and combustion	Jan – Dec 2011	600,000

^{*} Figures obtained from the Research Office, University of Sydney

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2011 Publications[†]

Book Chapters

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Malalasekera, W, Ibrahim, S, Masri, A R, Gubba, S, Sadasivuni, S 2011, Experience with the Large Eddy Simulation (LES) Technique for the Modelling of Premixed and Non-premixed Combustion, 8th International Conference on Heat Transfer, Fluid Mechanics and Thermodynamics (HEFAT2011), HEFAT, Mauritius, 398-407

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[†] Records obtained from the Integrated Research Management Application (IRMA), University of Sydney

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Journal Papers

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Fluid Dynamics

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Research Group



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Computational Fluid Dynamics (CFD); Stratified flows; Natural convection flows; Turbulence Dr Michael Kirkpatrick P: + 61 2 9351 2675 michael.kirkpatrick@sydney.edu.au

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Javadzadegan, Ashkan
Luthfi
Miles, Robert
Payami, Seyed Pezham
Tamaddon, Houman
Wong, Kaichung
Zecevic, Vanja
Zapletal, Erik

Research Grants*

Sponsor/ Grant Name	Chief Investigator [other AMME investigators]	Project Title	Duration	Awarded Amount (\$)
Australian Research Council/Discovery Projects	Armfield, Steven [Kirkpatrick, Michael]	Investigation and optimisation of displacement ventilation and cooling systems	Jan 2009 - Dec 2012	300,000
Australian Research Council/Discovery Projects	Kirkpatrick, Michael [Armfield, Steven]	The Dynamics of Turbulent Entrainment in Sheared Convective Boundary Layers	Jun 2011 - Dec 2013	350,000
Australian Research Council/Linkage Projects	Nagarathinam, Srinarayana [Armfield, Steven; Behnia, Masud]	Design tools for optimising data centre layout to minimise energy usage	Jan 2010 - Dec 2012	288,000
Australian Research Council/Discovery Projects	Williamson, Nicholas	Purging and destratifying of thermal and saline pools in Australia's inland rivers	Jan 2011 - Dec 2013	301,400

^{*} Figures obtained from the Research Office, University of Sydney

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2011 Publications[†]

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[†]Records obtained from the Integrated Research Management Application (IRMA), University of Sydney

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Graduates 2011

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Doctor of Philosophy

Aberra, Tilek

Numerical Investigation of Boundary Layer Instabilities in natural Convection

Allen, Thomas

Time-Optimal Active Decision Making

Barkby, Stephen

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Bertevas, Erwan

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Chen, Yuhang

Topology Optimization of Cellular Materials and its Application in Tissue Engine

Gillam, Natalie

Density Stratified Mixing from Cavities on Open-Channel Bends

Gomez Escobar, Jairo

Through-wall Radar Imaging Using Nonlinear Ultra-wideband Diffraction Tomograph

Juddoo, Mrinal

Experimental and Numerical study of Partially Premixed CNG-O2-N2 Flames

Karumanchi, Sisir Babu

Off-road Mobility Analysis from Proprioceptive Feedback

Kiang, Jademond

Multi-Physics Non-Linear Modelling and Testing of Magnetic Shape Memory Ni-Mn-Ga Single Crystals

Lawrance, Nicholas

Autonomous Soaring Flight for Unmanned Aerial Vehicles

Lee Wo, Duane

The Crystallization and Rheological Behaviour of Pigment-Polymer Blends in Tube Flow

Lin, Jiangzi

Topology Optimization and its Applications in Current and Future Aircraft Structure Design

Moscosco Lavagna, Luis

Computational Investigation of Wear in Centrifugal Slurry Pumps

Reid, Alistair

Gaussian Process Models for Analysis of Remotely Sensed Geo-Spatial Data

Rungsiyakull, Chaiy

Multiscale Bone Remodelling and Optimisation of Dental Implant Supported Prostheses

Tang, Chi Yan

Molecular Dynamics Simulation of Silicon Systems

Wang, Gongtao

On Fracture Toughness and Fatigue Resistance of Polymer/Nanoparticle Composites

Wood, David

Learning from Gross Motion Observations of Human-Machine Interaction

Master of Philosophy (Research)

Chen, Xi

Design and Implementation of Model Predictive Control Algorithms for Small Satellite Three-Axis Stabilization

Leslie, Angus

Broadband Noise Reduction of a Small UAV Propeller

Zeng, Ying

Fracture Toughness of Carbon Fibre Laminates with Nanoparticle Modification

Master of Engineering (Course work)

Abbad, Tasawar Syed Cao, Tianya Esparza, Arturo Jose Fernandes, Fernando Sam, Manfred Zheng Sundararajah, Niruparaj Tung, Man Fai Wang, Yu Zaman, Navid Iftekhar

Master of Professional Engineering

Barnes, Aidan Barrand, Zoe Anne Hossain, Musharrah Zafaranloo, Ali

Undergraduate Research- FSEA Racing Car

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Academic Staff Senior Technical Officer

Dr Lozzi, Andrei Elder, Greg

Formula SAE is a student engineering competition where teams design, construct and race a small open-wheeled racing car intended for use in weekend autocross competitions. All research, design and manufacture must be completed within a period of 12 months to prepare for the annual event held by the Society of Automotive Engineers Australasia. The three-day event scores teams on their design, costing and marketing skills as well as dynamic events of skid pad, acceleration, autocross and endurance.

Dr Andrei Lozzi on this year's FSEA Competition

We are thrilled and more than a little relieved to have returned from Melbourne having placed fifth in the 2011 Formula SAE competition – an amazing result to end a big year. The field consisted of 24 local and overseas teams. Doing well in Australia has to be seen as an achievement, at least because since 2004 three local teams have at times been the world's best. These have been Wollongong, RMIT and University of WA.

This year our team has shown the attributes necessary to finally turn an inspiration that came to us in 2008 into a reliable, fast and drivable car. We have built a great deal on the imagination, hard work and progress of past teams. There have been quite a few baffling problems that have baulked our progress, but ultimately this year thanks to intelligent and persistent good work, most plans have reached fruition.

Many of the members that are graduating this year have been in the team for three years. Each 'year' really begins in the previous December and ends in the current December. In 2011 the team has met during the week before Semester I, to debrief, discuss and distribute tasks. Designs were analyzed and manufacture got under way, before the July break. The almost completely new car was on the road to be tested and developed before the end of August.



Figure 1: Our successful 2011 team with many 3rd year students preparing for the 2012 competition

Undergraduate Research- FSEA Racing Car

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There have been many junior students, technicians and academics that have been very helpful, to whom we are grateful, but here I will just mention the thesis team that will graduate, the drivers and one resident technician.

Edward Jarvie Frame & suspension, team co-leader, inspiring, pushy & committed
Gwylim Johnstone Shafts & engine and team co-leader, inspiring, pushy & committed
Clare Young Human resources & management (an honorary and valued member)
Alex Chen Electronics, data logger, ECU, wiring & potential driver, an important chap

Ted Hackney Everything about brakes and good fun

Jonathan Stables

Lubrication & cooling system, provided a revealing piece of work

Benn Reid

Futuristic drive shafts & the reincarnation of Ben Hur on the track

Brayden Mead

Aerodynamics, lift & drag and the Pinin Farina of our styling department

Jordan McCulloch
Daniel Bartos
Shannon Beneforti
Luke Henry
Carmel Wilson
Suspension & frame flexure properties, possessing great strength
Air intake, the most in-depth & complete engine modeling
Design & manufacture of advanced practical wheel uprights
Research & testing into novel, light and cheap wheel centers
Steering system, a very difficult mechanism to perfect

Hamish Johnstone A very quick and scary driver
Ian Salteri A very quick and less scary driver

Greg Elder Most excellent machinist, test driver and advisor in all things practical

		Skid pad	Acceleration	AutoCross	Endurance/Econ	Cost	Presentation	Design	Total	Final Rank
Car#	Team	(/75)	(/50)	(/100)	(/425)	(/100)	(/50)	(/200)	Total	Filiai Kalik
66	Monash University	75.00	, ,	. ,	378.87	82.90	44.93	160.00	863.87	1
2	University of Western Australia	55.46	50.00	100.00	390.16	47.47	45.15	99.00	787.24	2
7	Edith Cowan University	23.66	47.47	76.15	323.28	64.97	36.76	200.00	772.30	3
47	The University of Auckland	33.43	8.50	63.32	273.87	72.59	50.00	175.00	676.71	4
22	University of Sydney	51.75	32.80	48.37	288.91	59.52	47.71	143.00	672.06	5
12	RMIT University	5.51	32.27	65.55	180.20	67.59	46.99	185.00	583.11	6
10	University of Wollongong	36.42	35.96	56.10	232.19	80.02	46.91	95.00	582.60	7
6	Osaka University	39.32	40.92	15.12	218.46	75.75	37.41	134.00	560.98	8
14	Curtin University	3.50	49.35	28.47	247.97	57.80	39.75	105.00	531.83	9
67	Nippon Institute of Technology	48.77	31.78	19.61	224.81	73.22	30.92	97.00	526.10	10
46	Queensland University of Technology	35.41	34.87	47.27	247.50	37.63	43.90	76.00	522.56	11
101	University of Melbourne	47.23	47.47	29.38	162.96	62.28	49.02	120.00	518.34	12
8	University of Adelaide	28.90	40.38	37.41	178.76	62.94	45.29	94.00	487.68	13
3	University of Newcastle	6.81	39.22	6.31	202.31	55.36	41.18	92.00	443.19	14
41	University of Queensland	37.48	37.59	7.48	148.15	53.73	48.49	98.00	430.92	15
63	University of New South Wales	28.38	42.66	32.00	32.00	60.21	47.84	138.00	381.09	16
59	University of Technology , Sydney	35.75	43.26	55.04	32.00	60.13	38.91	116.00	381.08	17
15	University of NSW - ADFA	42.86	45.67	5.00	1.00	77.22	45.74	150.00	367.48	18
88	RMIT University - EV	0.00	0.00	5.00	32.00	92.50	49.58	146.00	325.08	19
21	Toyko Denki University	0.00	0.00	5.00	5.00	80.71	34.29	126.00	250.99	20
17	Swinburne University - EV	3.50	24.49	5.00	0.00	70.70	41.85	101.00	246.54	21
5	Deakin University	0.00	22.66	5.00	14.00	59.52	42.65	101.00	244.83	22
9	Indian Institute of Technology Roorkee	0.00	0.00	0.00	32.00	73.50	38.60	74.00	218.10	23
4	Bangalore Institute of Technology	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	24
18	NED University, Pakistan	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	24

Figure 2: Formula SAE Australasia 2011 Overall Results

Student Research Showcase

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Engineering Sydney hosted its annual Research Conversazione on Friday 28 October 2011. Heading into its 23rd year, Research Conversazione has become the premier research event within our faculty. Held annually in October, this event allows the faculty to showcase high calibre research and projects undertaken by undergraduate and postgraduate students with a focus on innovative, applied research that responds to national and international needs, as well as engaging with various new approaches and applications.

There were 42 posters presented from the School of Aeronautical, Mechanical & Mechatronic Engineering which were judged by the relevant industry representatives and academics from the Faculty for the following prizes generously sponsored by Shelston IP and Watermark Patent Attorneys.

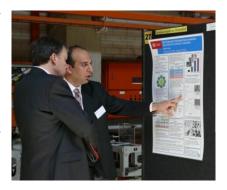


Shelston IP Best Poster Awards - Undergraduates

Henry Langston (Aeronautical) Alisa Pham (Biomedical) Zichao Wu (Mechanical) Sarah McDonald (Mechatronics) Rishi Verma & Jiro Funamoto (Space)

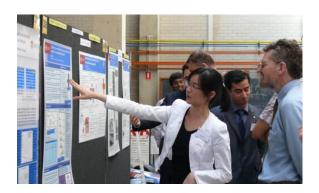
Shelston IP Best Poster Awards - Postgraduates

Srinivas Vasista (Aeronautical) Sayediman Roohaniesfahani (Biomedical) Song Ni (Mechanical) Lashika Medagoda (Mechatronics) Calvin Hung (Space)



Watermark Best Poster Awards in Biomedical Engineering

Ben Davies (Undergraduate) Ashkan Javadzadegan (Postgraduate)



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Research Income Awarded in 2011 for Projects Commencing in 2012^*

ARC Grants	\$3,606,797
NHMRC Grants	\$746,067
Industry/ Private Funds	\$ 1,154,676
Total	\$5,507,540

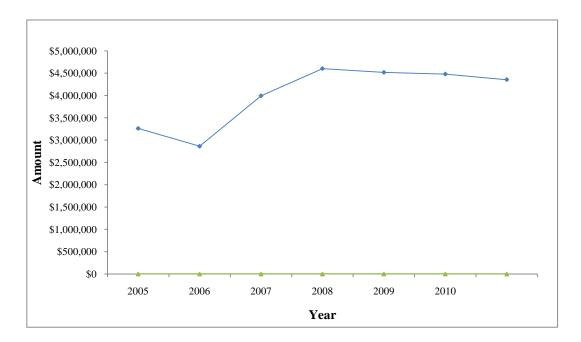


Figure 1: Successful ARC and NHMRC Funding/ Year (2005 – 2011)

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^{*} Figures obtained from the Research Office, University of Sydney

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Research Output

The publications reported and approved for the University's **Higher Education Research Data Collection** (HERDC) are reported below.

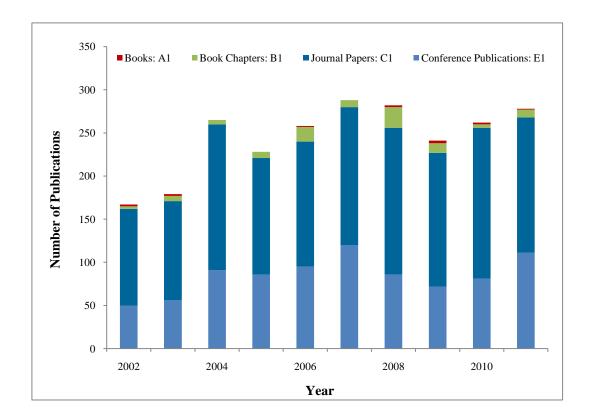


Figure 2: Research Publications 2002- 2011

A1: Authored research books published by commercial publisher

B1: Authored research chapters in commercially published books

C1: Refereed articles in peer reviewed journals

E1: Full length peer reviewed papers published in conference proceedings

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Postgraduate Supervision and Completions

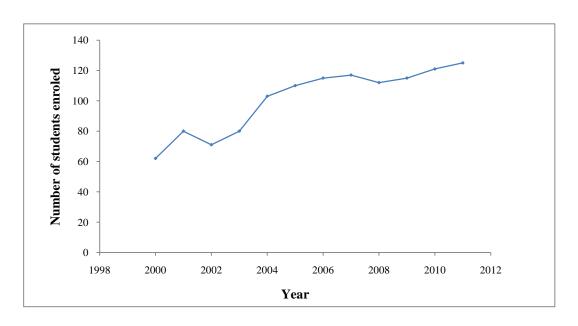


Figure 3: Total number of enroled Master of Philosophy and PhD students (2000-2011)

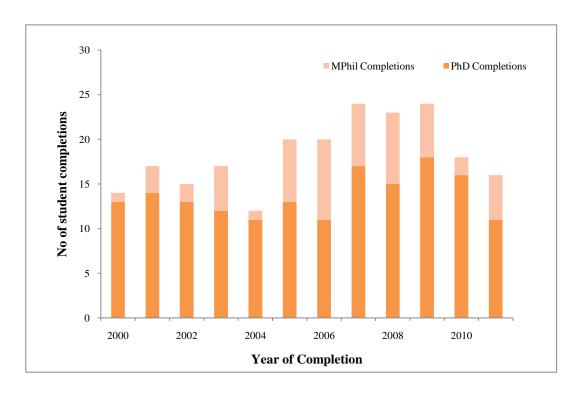


Figure 4: PhD and MPhil completions. (2000 – 2011)